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SICE 2019

The SICE Annual Conference 2019 (SICE 2019), organized by the Society of Instrument and Control Engineers (SICE), will be held in September, 2019, in Hiroshima, JAPAN. The SICE Annual Conference 2019 is an international conference covering a broad range of fields from measurement and control to system analysis and design, from theory to application, and from software to hardware. The technical program of SICE 2019 will consist of plenary and invited talks, tutorial courses, and workshops, as well as oral and interactive sessions.

Important Dates (Tentative)

Paper Submission Webpage Open
Proposal of Workshop and Tutorials
Proposal of Organized Sessions
Submission for Regular Papers and Position Papers
Notification of Paper Acceptance
Submission of Final Camera-ready Papers

January 1, 2019
February 15, 2019
February 28, 2019
March 15, 2019
June 1, 2019
July 1, 2019

Conference Venue

SICE 2019 will be held at Higashi-Senda Innovative Research Center of Hiroshima University. Higashi-Senda Innovative Research Center is located at the center of Hiroshima city. It is easily accessible from Hiroshima station by Tram. Hiroshima has two world heritages. One is The Hiroshima Peace Memorial. And the other is Itsukushima Shinto Shrine.

Technical Co-Sponsors (Tentative)

IEEE Control Systems Society (CSS); IEEE Robotics and Automation Society (RAS); IEEE Industrial Engineering Society (IES); Institute of Control, Robotics and Systems (ICROS); International Society of Automation (ISA); Technical Committee on Control Theory (TCCT), Chinese Association of Automation (CAA); Japan Electric Measuring Instruments Manufactures' Association (JEMIMA); Electrical Engineering/Electronics, Computer, Telecommunications and Information Technology (ECTI) Association

In Association with (Tentative)

The Chinese Association of Automation (CAA); China Instrument and Control Society (CIS); Asian Control Association (ACA); Hiroshima University



Paper Submission

The SICE Annual Conference 2019 accepts two types of submissions for review:

Regular paper: Full papers (6 pages in conference format) must be submitted for review. The accepted papers will be submitted to the IEEE Xplore Digital Library. Normal length for the final manuscript of the regular paper is 6 pages. Paper exceeding 6 pages may be submitted upon payment of overlength page charges. A maximum of 2 extra pages above 6 pages are permitted.

Position paper: Extended abstracts (2-4 pages in conference format) must be submitted for review. This category is provided for authors who want to present a timely review of research, a case study, and so on. This type of paper will NOT be included in the IEEE Xplore Digital Library.

Both types of papers should be written in English, and will be included in the conference proceedings. The detailed submission policy is found on the conference web page.

Organized Sessions, **Workshops Tutorials**

The goal of organized session is to provide focused discussions on a new topic or innovative applications of a new approach. Each session consists of 6 papers, which reviewed via the normal review process. Both regular and position papers can be included in a session. For session proposals, it is recommended to include a brief statement of the session focus, together with the submission of the individual papers. We also encourage proposals for workshops or tutorials that address technical topics with highly anticipated level of interest, impact, and creativity.





Photo courtesy of Hiroshima Prefecture

Topics

Measurement

Sensors and Transducers Signal and/or Image Processing **Identification and Estimation** Opto-Electronic Measurement **Remote Sensing** Mass and Force Measurement **Temperature Measurement** Ultra-High Precision Measurement **Analytical Measurement** Standard of Measurement Flow Measurement and Control **Networked Sensor System**

Systems and Information

System Engineering **Human-Machine Systems Intelligent Systems Autonomous Decentralized Systems** Computational Intelligence **Discrete Event Systems** Social Systems Hypercomputes Molecular Robotics Relationality-Oriented Systems Science **Smart Mobility Systems**

Control

Multivariable Control Nonlinear Control Robust Control Adaptive and Optimal Control Intelligent Virtual Reality Systems Control Computer Aided Design Modeling, System Identification and **Estimation Process Control** Mechanical Systems Control Guidance and Flight Control **Power Systems Control**

Industrial Applications

Process Automation Factory Automation Laboratory Automation Information Management Systems SCADA and Network Systems Manufacturing Systems **Transportation Systems** Micro and Nano Devices **Components and Devices**

System Integration

Mechatronics Systems Robotic and Automation Systems Human Interfaces Entertainment Systems Medical and Welfare Systems Safety, Environment and Eco-Systems Agricultural and Bio-Systems **Rescue Systems** Simulation of Large Systems **Network System Integration**

Life Engineering

Integrative Biophysical Engineering and **Informatics** Biological and Physiological Engineering Electrophysiology and Kinesiology **Ubiquitous Healthcare**

Others





Contact

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