1. Goal
- Contribution toward realization of intelligent vehicle through discussions and information exchanges among researchers and engineers in various fields.
- Deepening and making intelligence of not only single vehicle but also multi-vehicle system.

2. Problem
- Robust sensing and control for intelligent vehicles.
- Environmental perception by LIDAR and Vision.
- Multi-sensor fusion and dependable sensing.
- Multi-vehicle cooperation by vehicle-to-vehicle and vehicle-to-infrastructure communication.

3. Strategy
- Information exchange about intelligent vehicle through lectures, seminars and organized sessions.
- Visit to universities and companies to observe and discuss state-of-the-art technologies of intelligent vehicle systems.

4. Activity Plan
- Organized session, “Sensing, Control and Safety System for Intelligent Vehicle” on ICCAS-SICE 2009
- Technical visit to university and company

Organizers (2009)
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